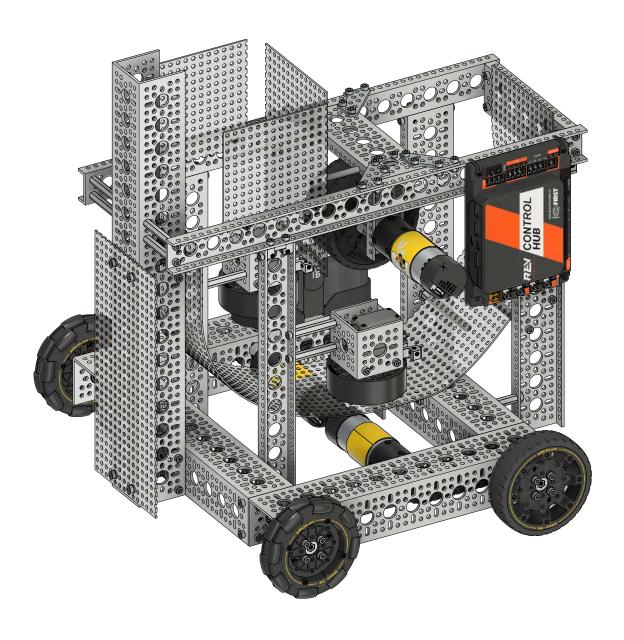
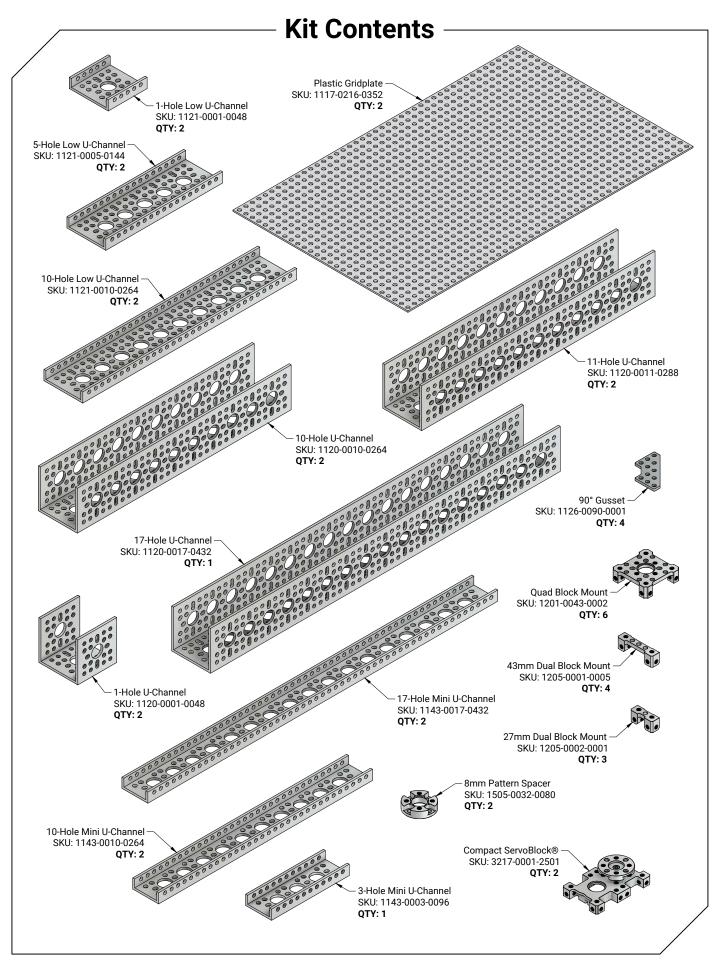
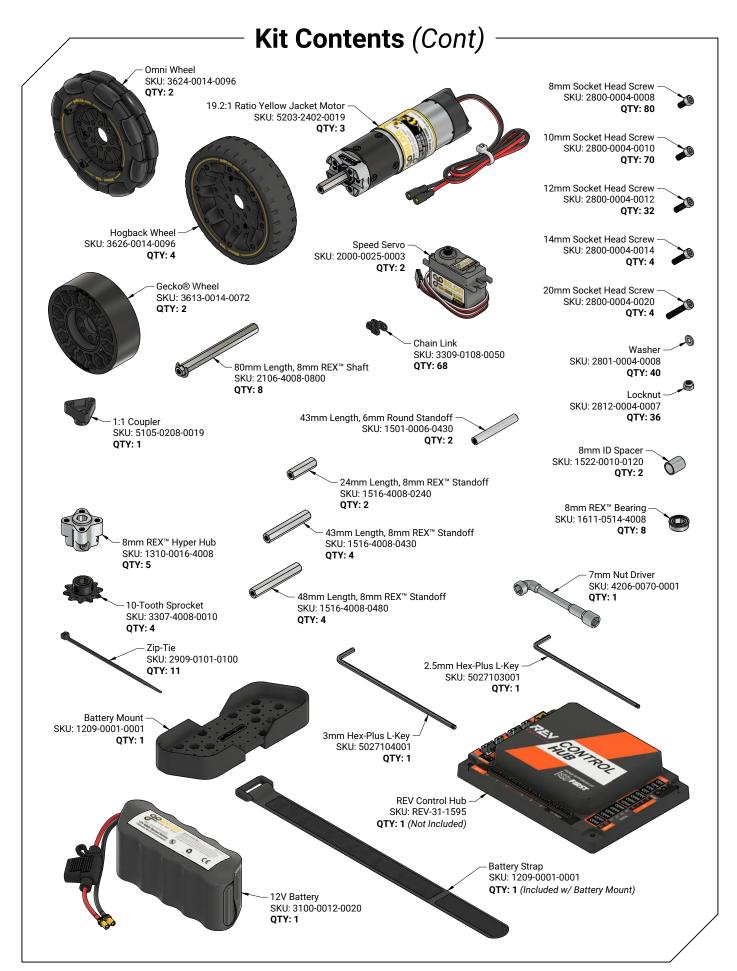
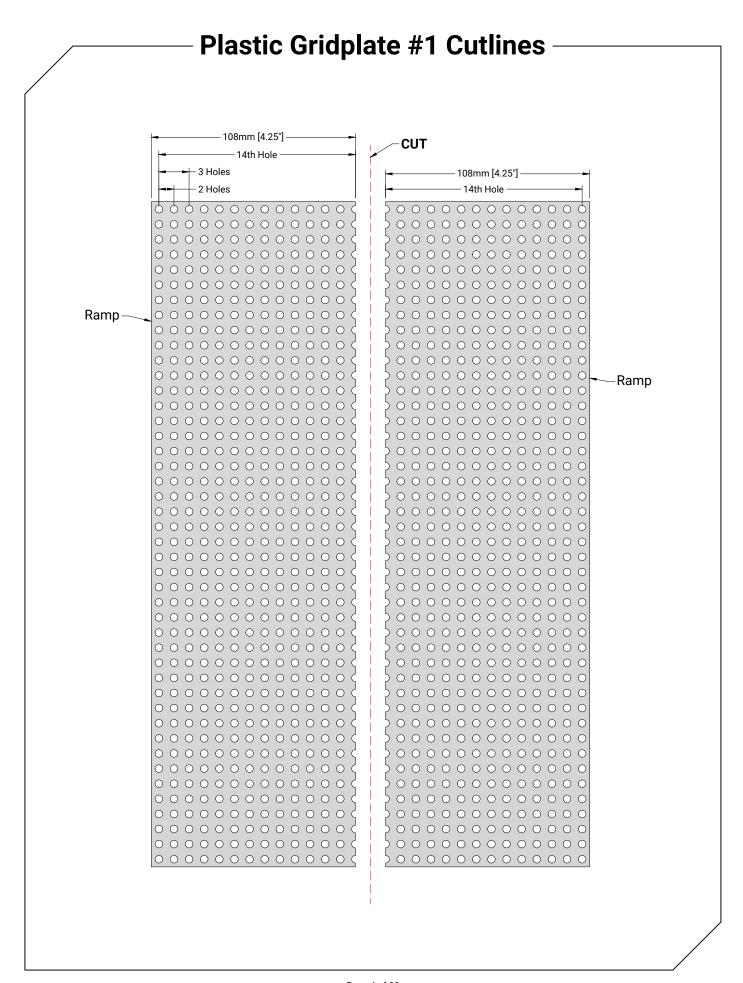


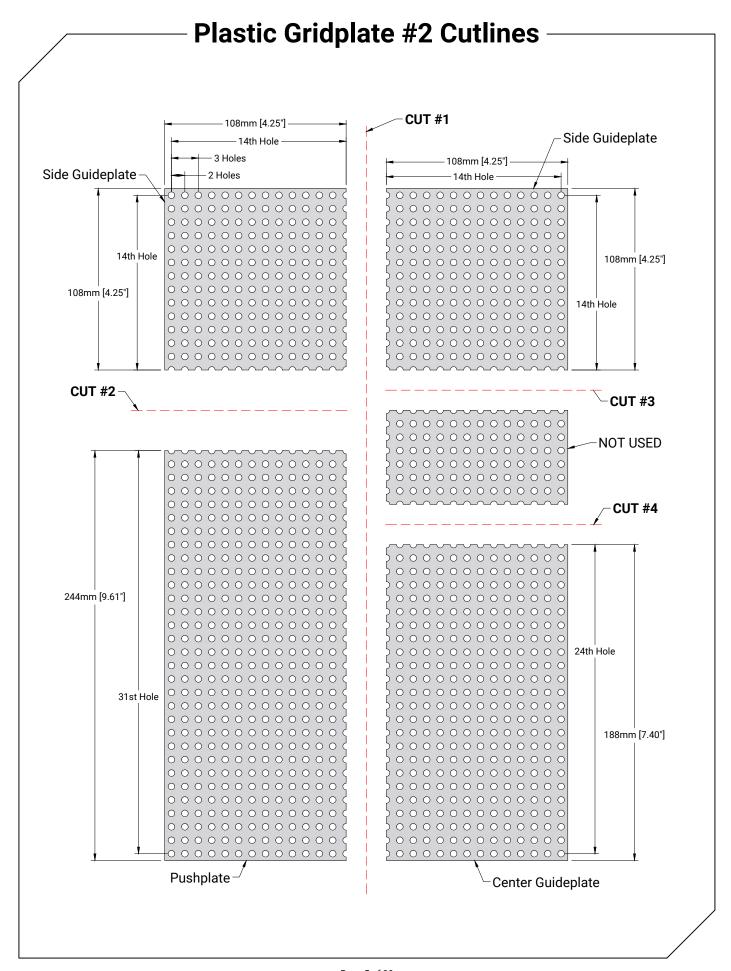
## Assembly Instructions for FTC Starter Bot (for DECODE™) Built from the FTC Starter Kit (SKU: 3200-4008-2526)

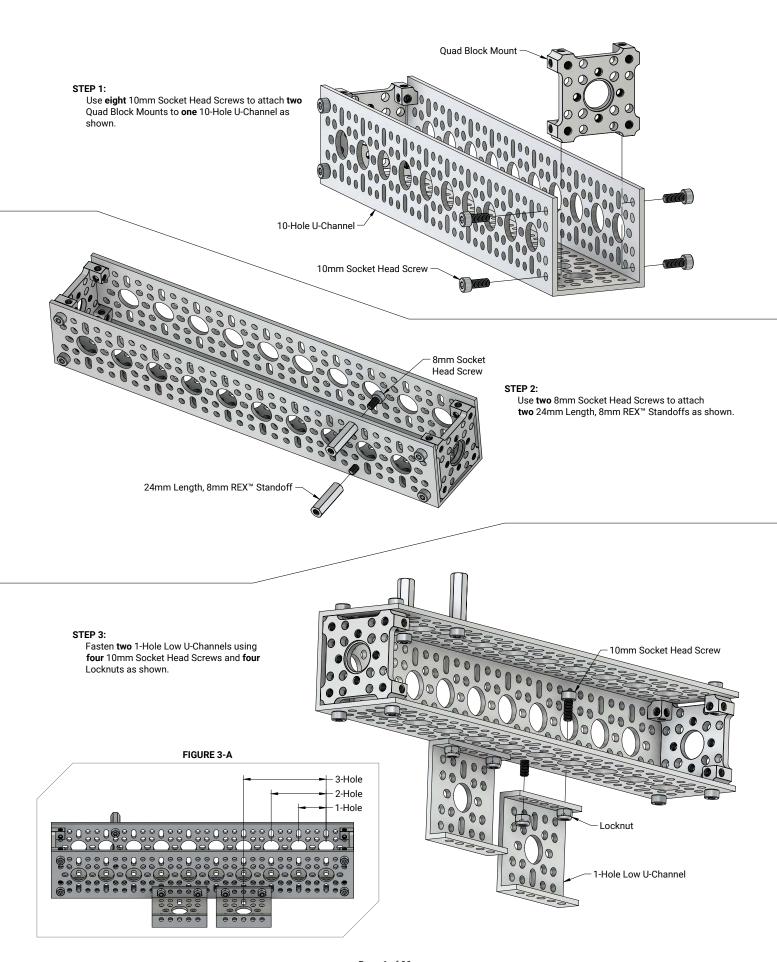




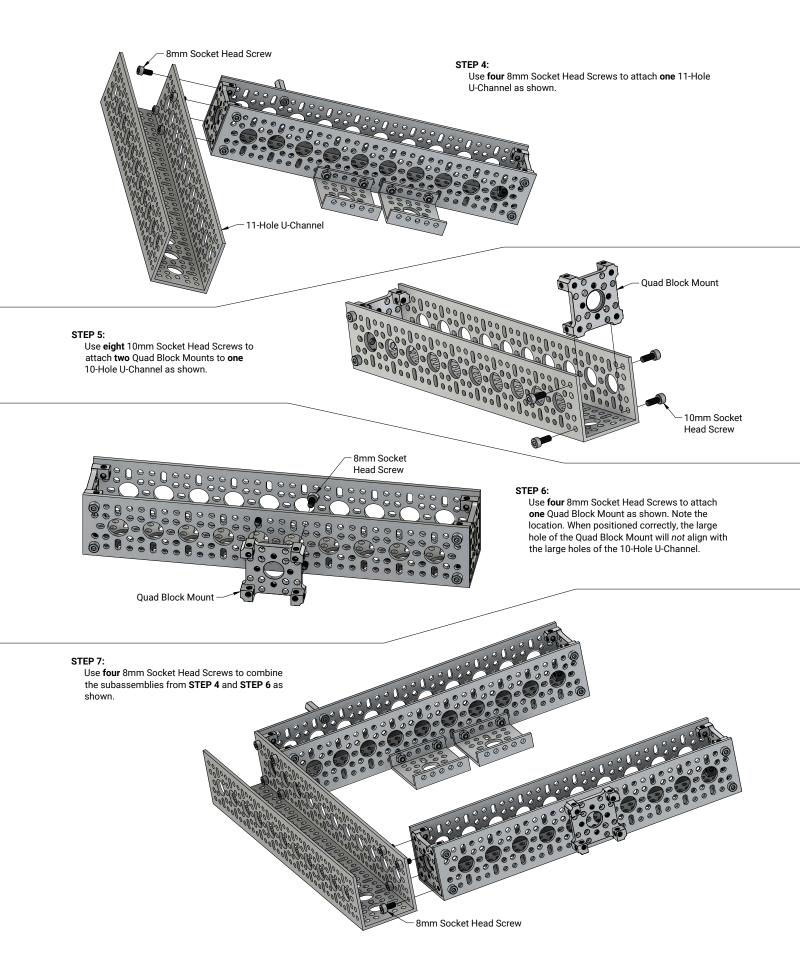




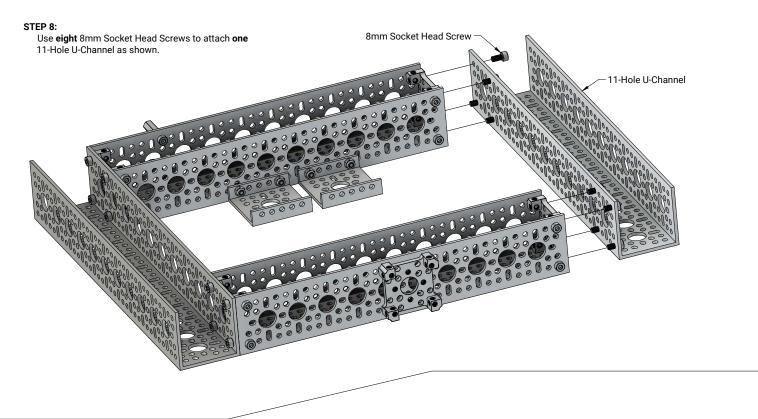




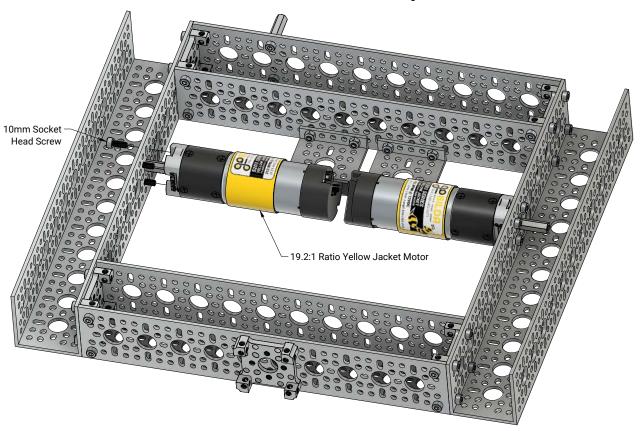
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STEP 9: Mount two 19.2:1 Ratio Yellow Jacket Motors using eight 10mm Socket Head Screws as shown.



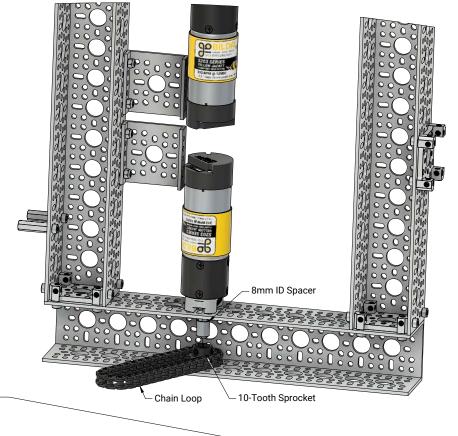


Use **thirty-four** Chain Links to create a Chain Loop (FIGURE 10-A).

Slide the Chain Loop, **one** 10-Tooth Sprocket, and **one** 8mm ID Spacer onto the 19.2:1 Ratio Yellow Jacket Motor as shown.





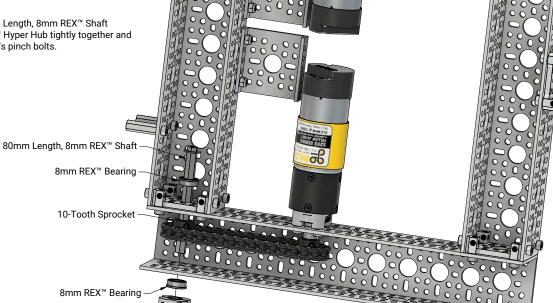


#### **STEP 11:**

Position **one** 10-Tooth Sprocket into the Chain Loop.

Slide **one** 80mm Length, 8mm REX™ Shaft through **two** 8mm REX™ Bearings, **one** 8mm REX™ Hyper Hub, and the 10-Tooth Sprocket. Note the orientation of the 8mm REX™ Bearings.

Hold the 80mm Length, 8mm REX™ Shaft and 8mm REX™ Hyper Hub tightly together and tighten the hub's pinch bolts.

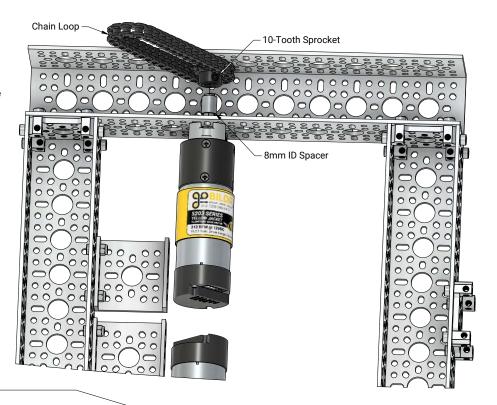


8mm REX™ Hyper Hub

#### **STEP 12:**

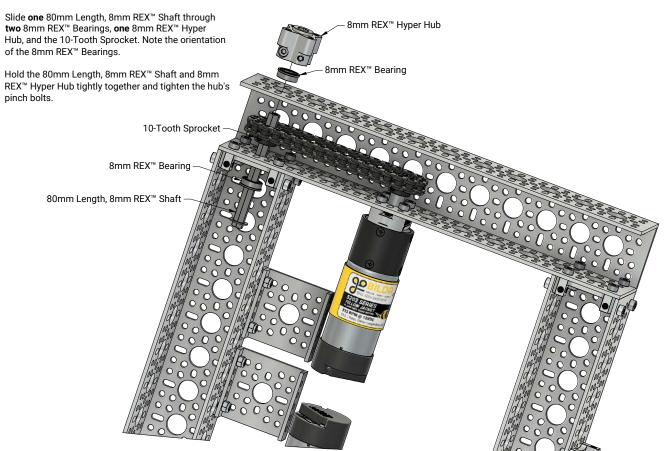
Use **thirty-four** Chain Links to create a Chain Loop.

Slide the Chain Loop, **one** 10-Tooth Sprocket, and **one** 8mm ID Spacer onto the 19.2:1 Ratio Yellow Jacket Motor as shown.

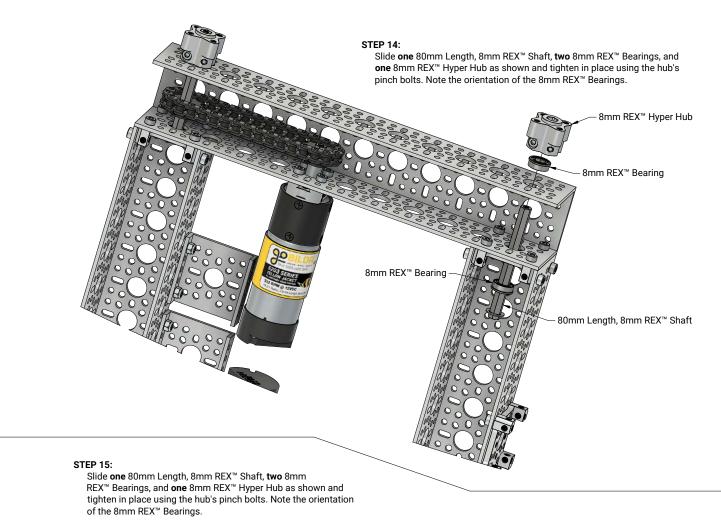


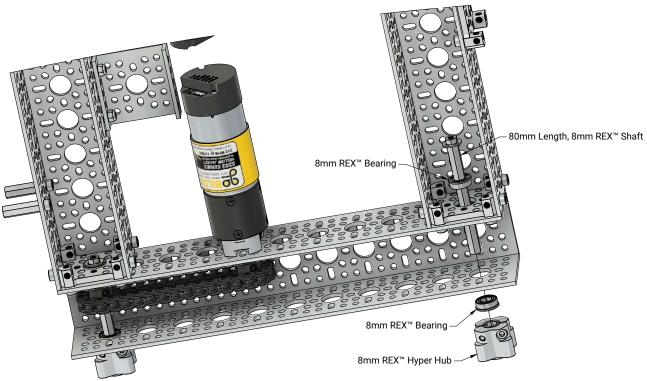
#### **STEP 13:**

Position one 10-Tooth Sprocket into the Chain Loop.



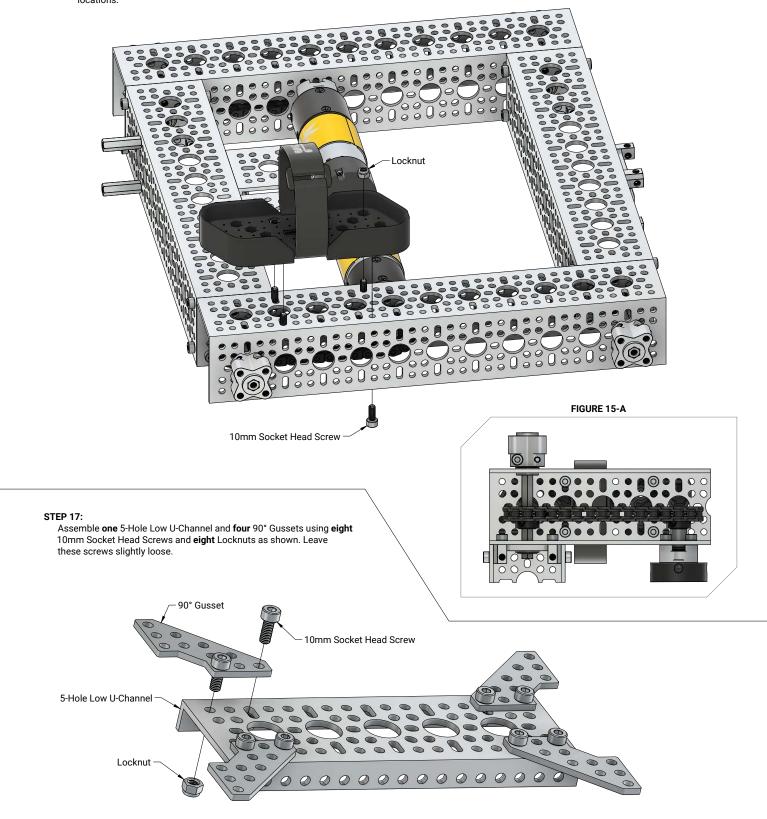
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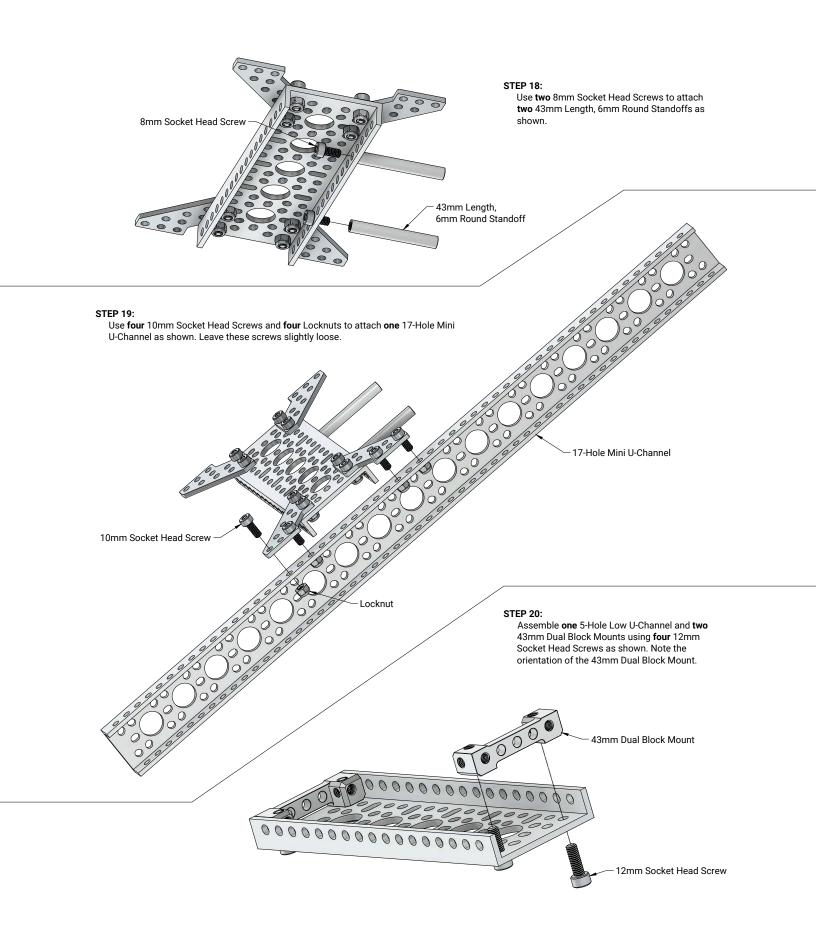


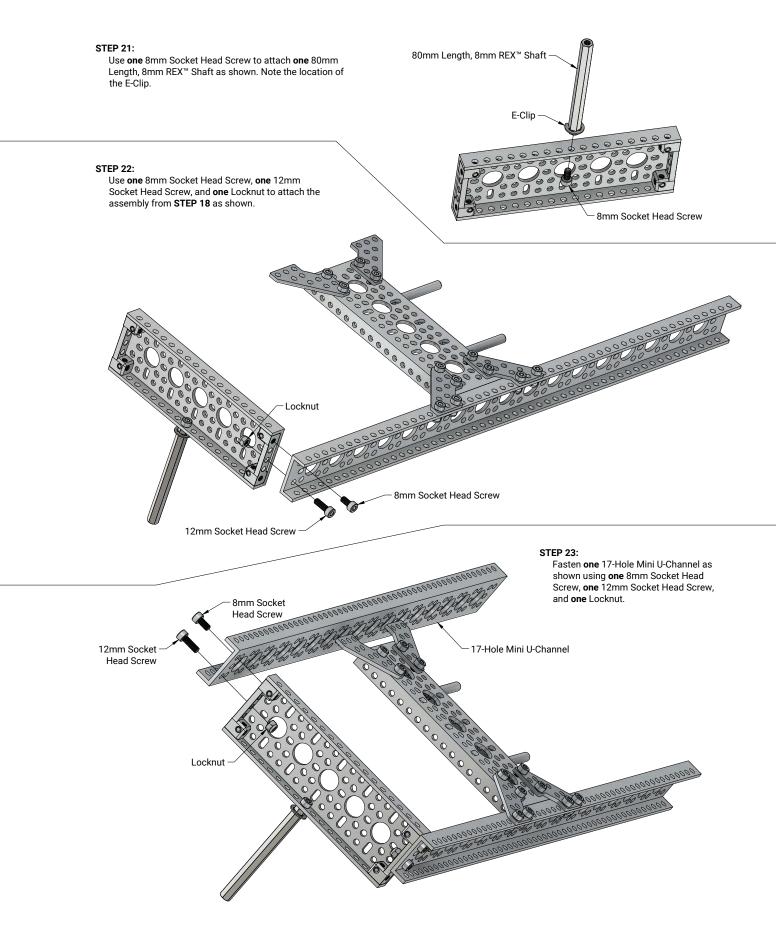


#### STEP 16:

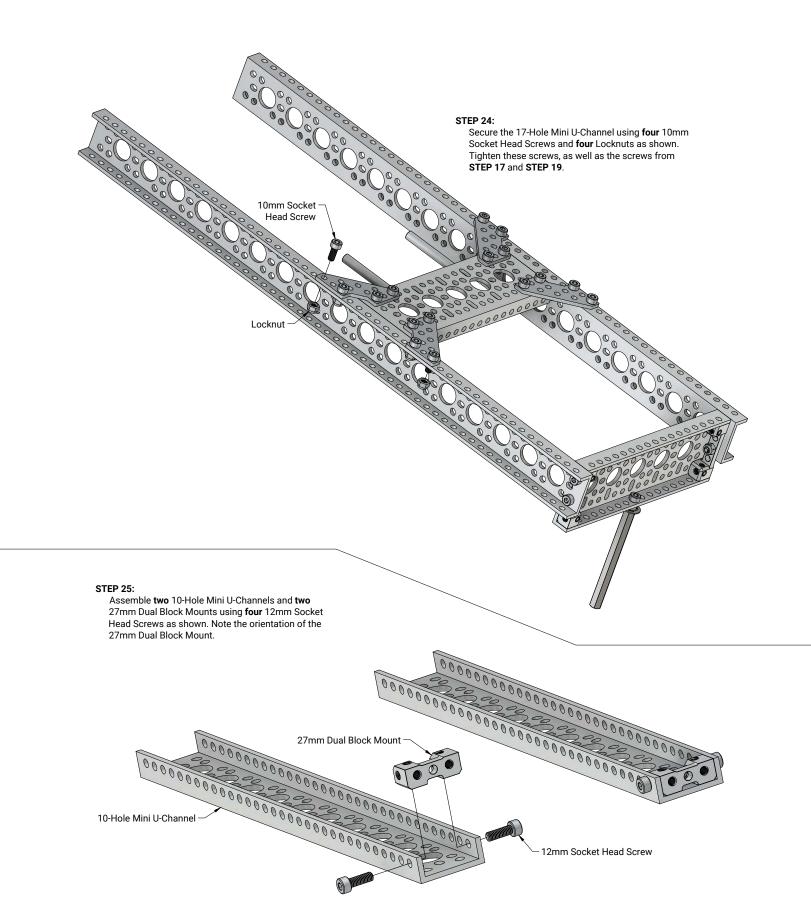
Use **four** 10mm Socket Head Screws and **four** Locknuts to fasten **one** Battery Mount and **one** Battery Strap as shown. Note the screw locations.

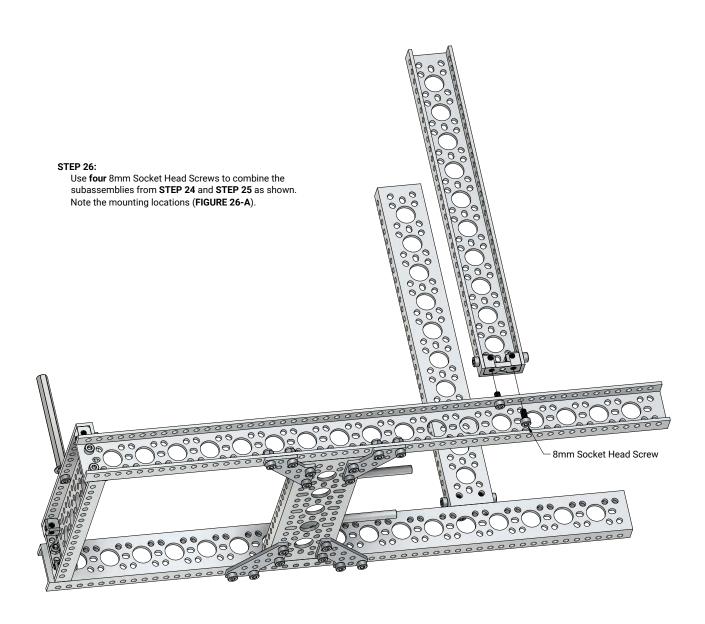


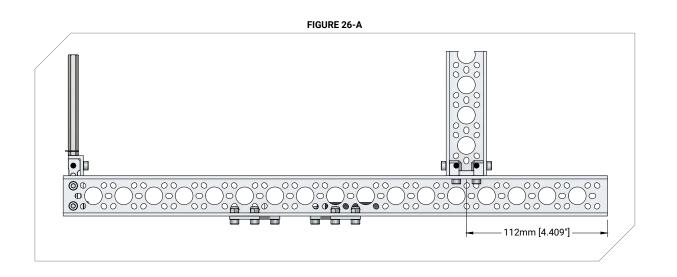




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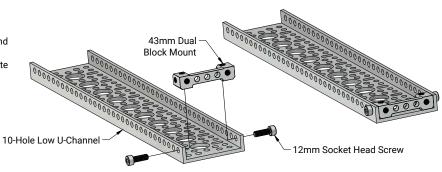


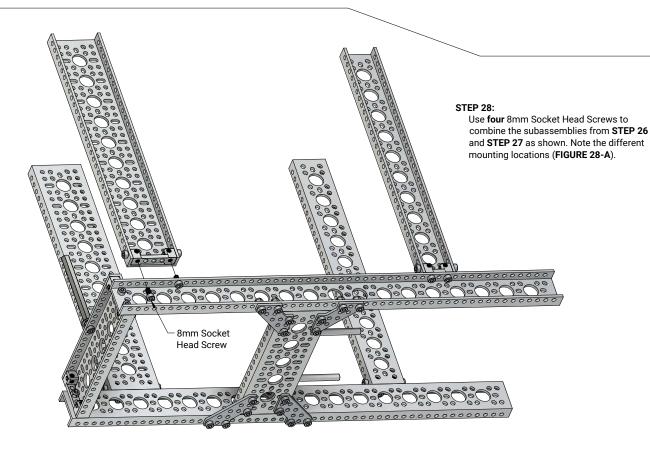


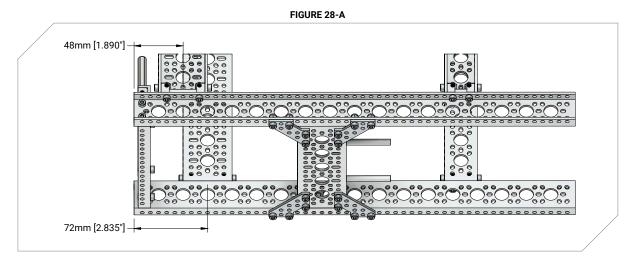


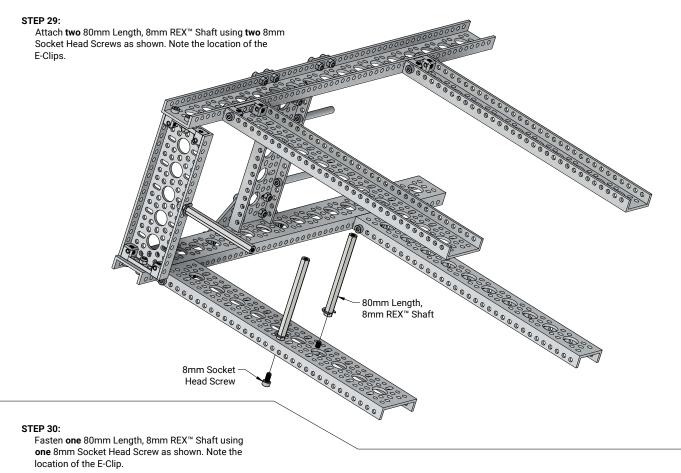


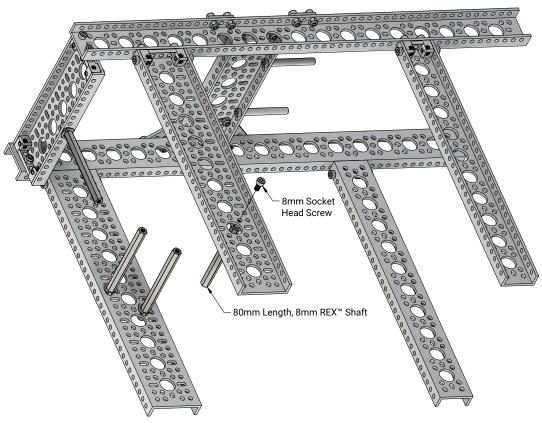
Assemble **two** 10-Hole Low U-Channels and **two** 43mm Dual Block Mounts using **four** 12mm Socket Head Screws as shown. Note the orientation of the 43mm Dual Block Mounts.



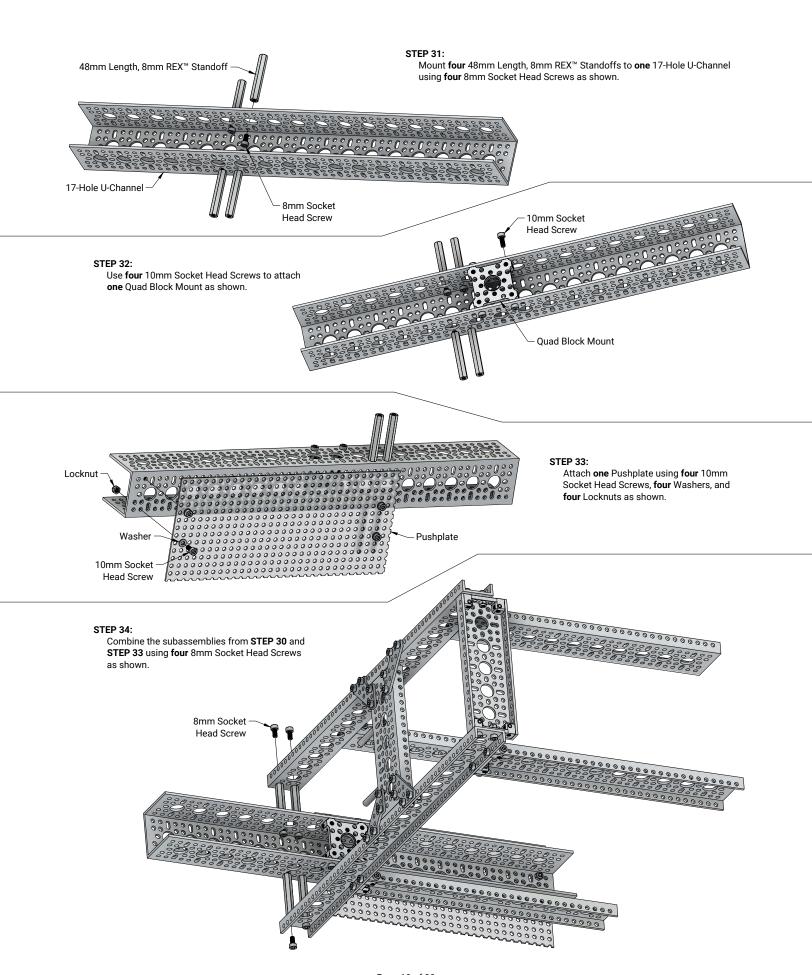






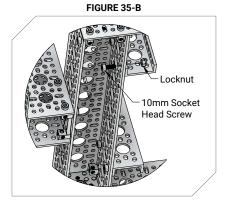


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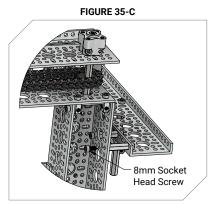


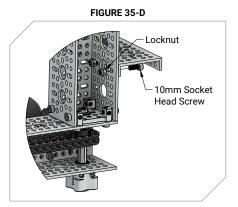
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STEP 35: Combine the subassemblies from STEP 16 and STEP 34: Use **four** 10mm Socket Head Screws as shown in **FIGURE 35A**. Use four 10mm Socket Head Screws and four Locknuts as shown in FIGURE 35B. Use two 8mm Socket Head Screws as shown in FIGURE 35C. Use two 10mm Socket Head Screws and two Locknuts as shown in FIGURE 35D. **B**) (C)FIGURE 35-A



10mm Socket **Head Screw** 





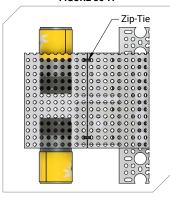
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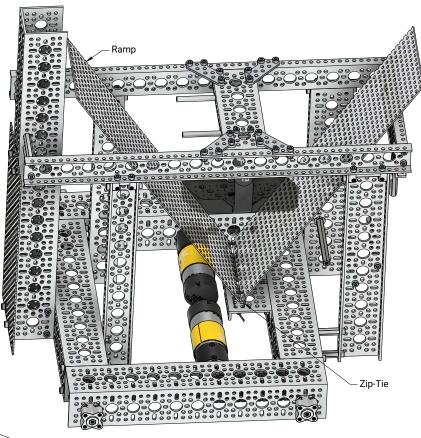


Use two Zip-Ties to fasten two Ramps in place as shown.

Make sure the "heads" of the Zip-Ties are below the 1-Hole Low U-Channel and that the Ramps both bend into position and lie flat against the 1-Hole Low U-Channels (**FIGURE 36-A**).

FIGURE 36-A





Zip-Tie

### Washer **STEP 37:** Push the first Ramp into place and fix in place using four Washers and four 8mm Socket 8mm Socket Head Screws as shown (FIGURE 37-A). **Head Screw** Push the second Ramp into place and fasten in position using two Zip-Ties as shown (FIGURE 37-B). Make sure the heads of the Zip-Ties are within the 5-Hole Low U-Channel (behind the ramp).

## FIGURE 37-A

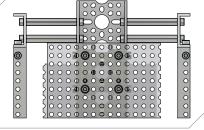
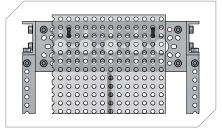


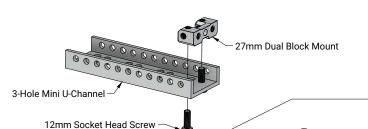
FIGURE 37-B



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Attach **one** 27mm Dual Block Mount to **one** 3-Hole Mini U-Channel as shown using **two** 12mm Socket Head Screws. Note the orientation of the 27mm Dual Block Mount.



#### STEP 39:

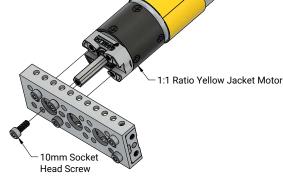
Convert **one** 19.2:1 Ratio Yellow Jacket Motor to a 1:1 Ratio Yellow Jacket Motor using **one** 1:1 Coupler (**FIGURE 39-A**). Attach the 1:1 Ratio Yellow Jacket Motor using **four** 10mm Socket Head Screws as shown.

#### FIGURE 39-A

Watch this video to see how to convert a 19.2:1 Ratio Yellow Jacket Motor to a 1:1 Ratio Yellow Jacket Motor: <a href="http://bit.ly/41fQtuj">http://bit.ly/41fQtuj</a>







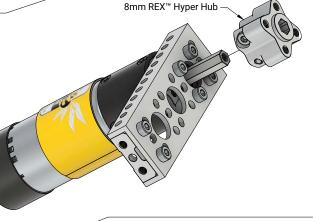
#### **STEP 40:**

Attach **one**  $8mm REX^{m} Hyper Hub as shown.$ 

A credit card is approximately 1mm thick and can be helpful in spacing the 8mm REX™ Hyper Hub away from the 10mm Socket Head Screws to achieve proper alignment.

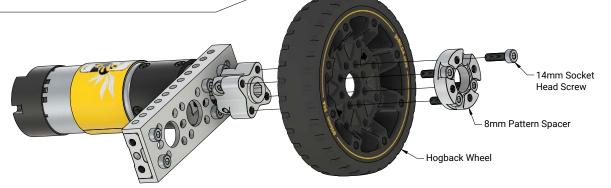
#### FIGURE 40-A

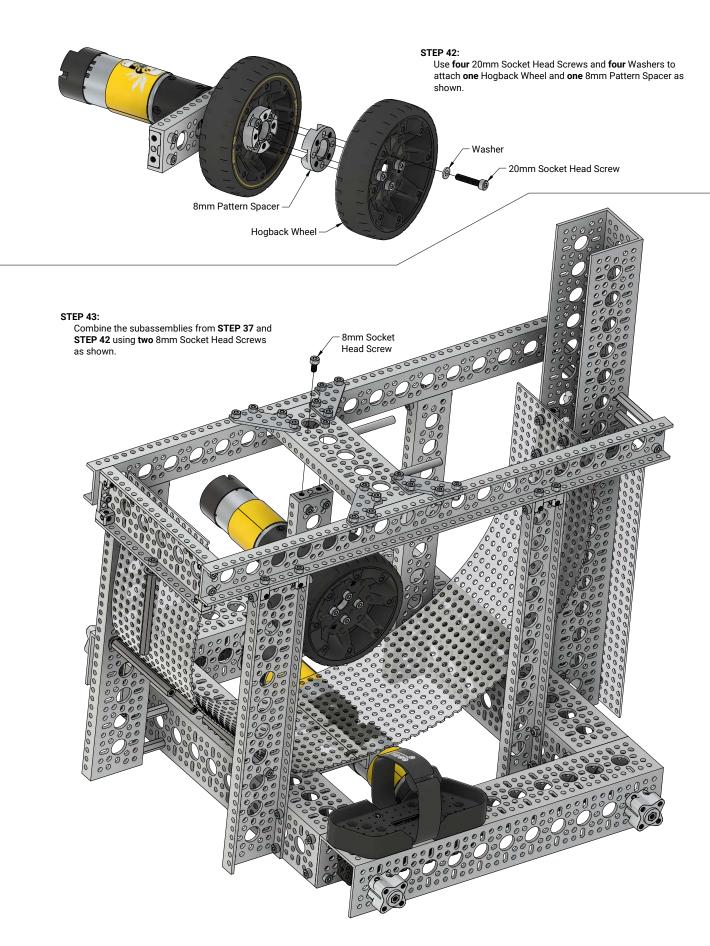




#### **STEP 41:**

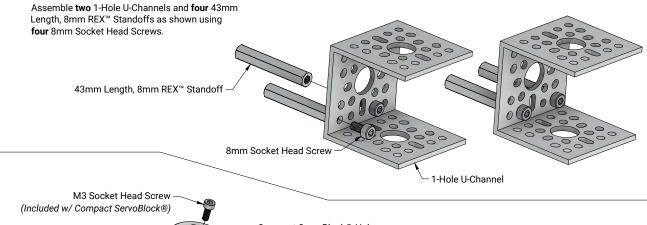
Attach **one** Hogback Wheel and **one** 8mm Pattern Spacer using **four** 14mm Socket Head Screws as shown.

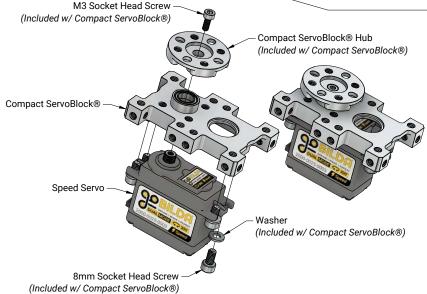




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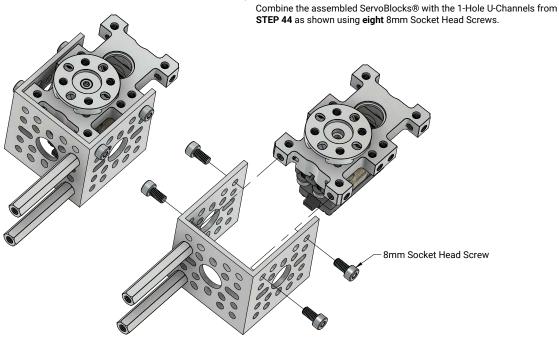




#### STEP 45:

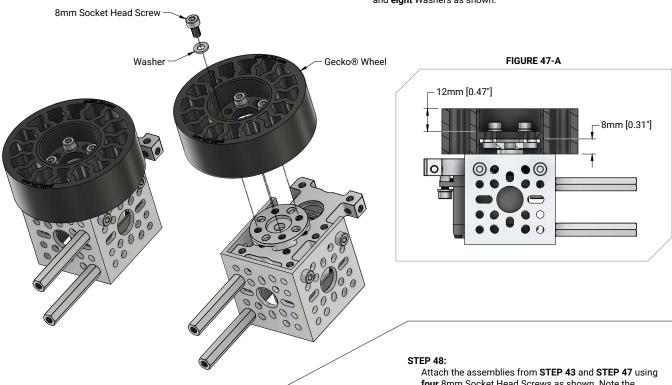
 $\label{lem:compact_servoBlocks} Assemble \ \mbox{two Compact ServoBlocks} \ \mbox{with two Speed Servos as shown}.$ 

#### STEP 46:

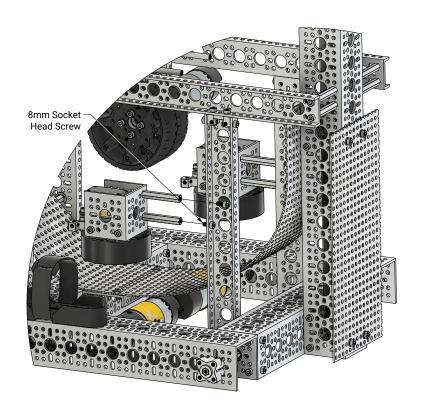


**STEP 47:** 

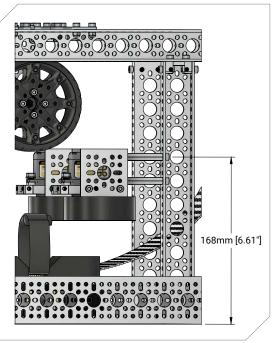
Attach two Gecko® Wheels with eight 8mm Socket Head Screws and eight Washers as shown.

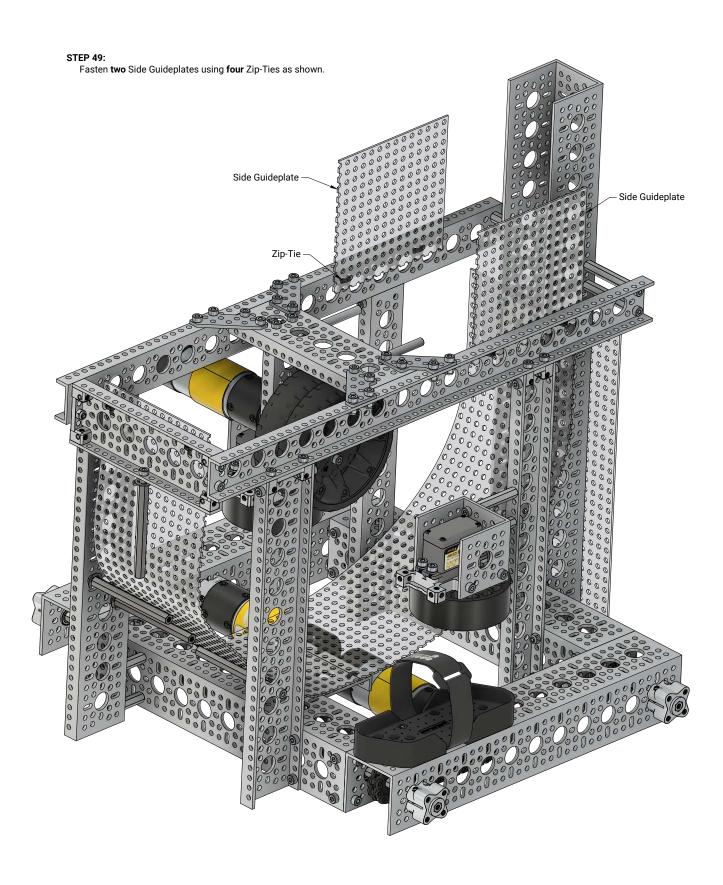


Attach the assemblies from STEP 43 and STEP 47 using four 8mm Socket Head Screws as shown. Note the locations (FIGURE 48-A).



#### FIGURE 48-A

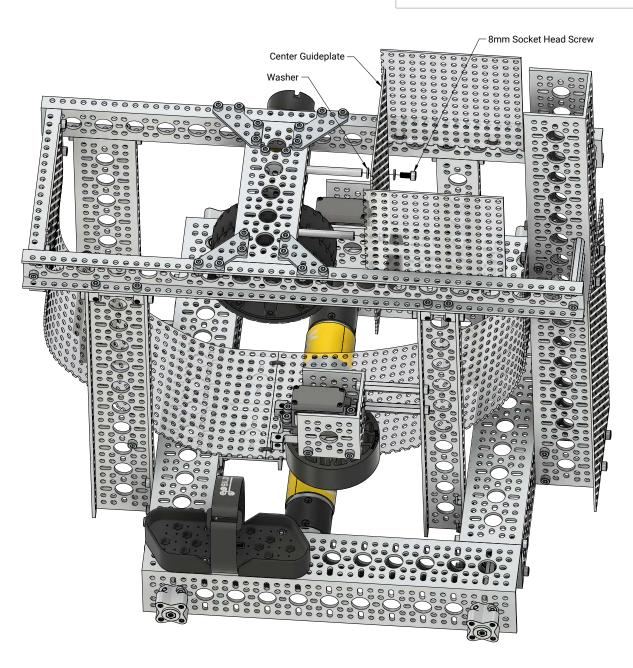


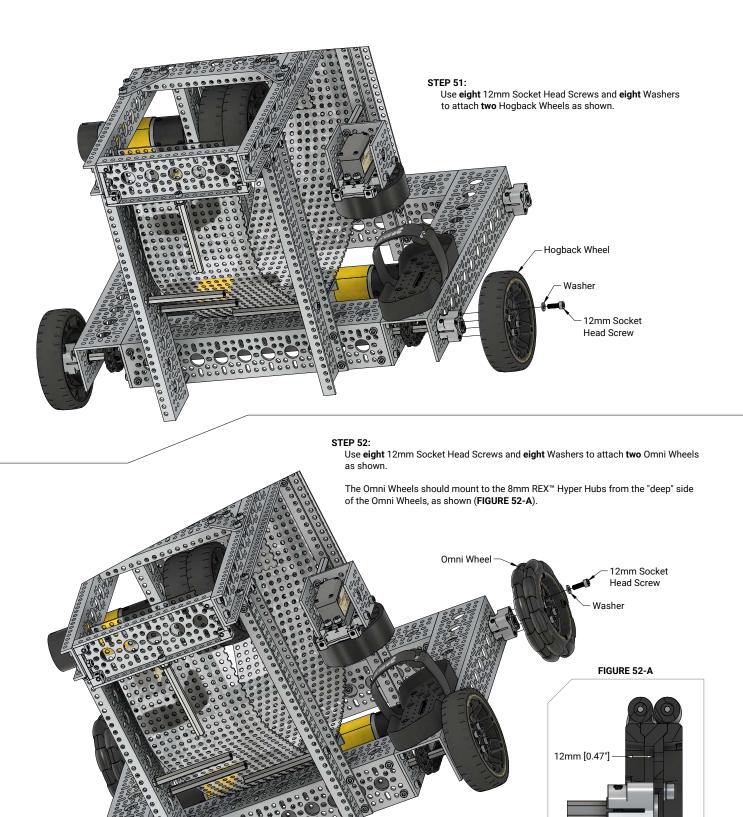


# FIGURE 50-A 100mm [3.94"]

#### STEP 50:

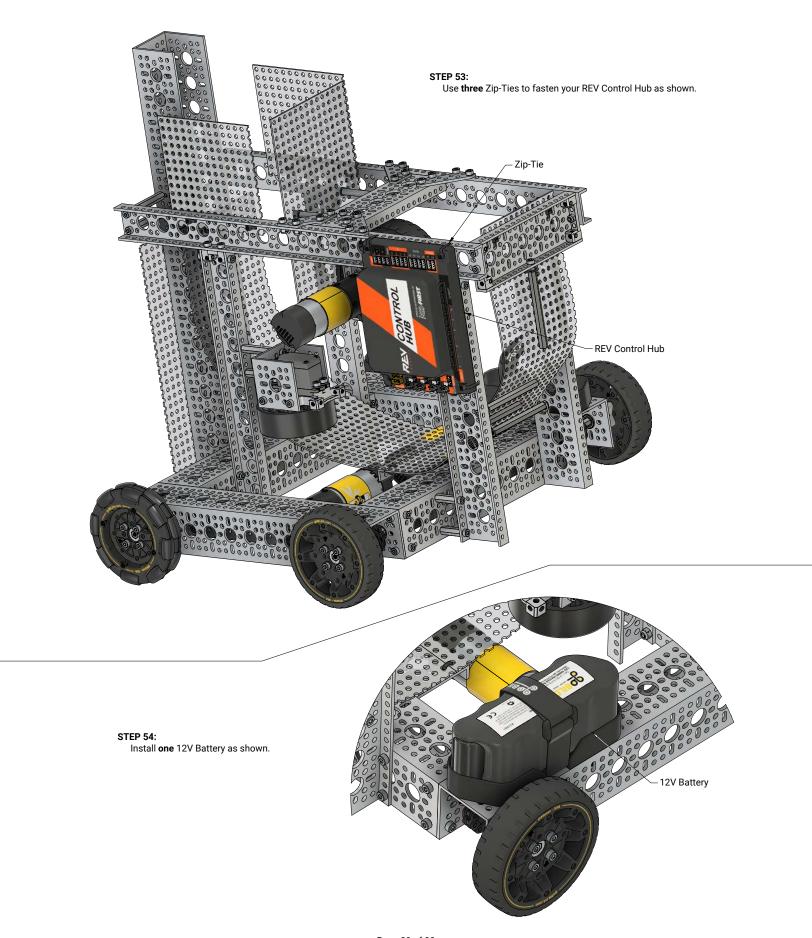
Use **two** 8mm Socket Head Screws and **four** Washers to fasten **one** Center Guideplate as shown. The height should match the Side Guideplates (**FIGURE 50-A**).





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8mm [0.31"]



#### **Great Job!**

You've completed the assembly! You're almost there—next up is wiring and programming your robot. Remember, this is just the beginning of what you can accomplish. Stay curious, and enjoy the journey ahead!

